

LECTURE 8: CONFORMAL MAPPING

3.1 Wedges and channels

3.1.1 The basic idea

Suppose we wish to find the flow due to some given singularities (sources, vortices, *etc.*) in a region $R \subset \mathbb{C}$ with impermeable boundary ∂R . The idea is to perform a *conformal mapping* $\zeta = g(z)$ so that the region R in the z -plane is mapped to a much simpler region \hat{R} in the ζ -plane (for example a half-space). As shown schematically in Figure 3.1, any sources, vortices, *etc.* present in R will be mapped to corresponding singularities in \hat{R} . Now we can hopefully solve the transformed problem, for example using the method of images, to get the complex potential $W(\zeta)$. Then we just have to invert the conformal mapping to recover the complex potential in the original z -plane, namely

$$w(z) = W(g(z)). \quad (3.1)$$

We begin by illustrating the general approach using a simple example.

Example 3.1 Source in a wedge

Suppose fluid occupies the wedge-shaped region $0 < \theta < \alpha$, where θ is the usual polar angle, with impermeable walls on $\theta = 0$ and $\theta = \alpha$. We wish to find the flow due to a source of strength Q placed at a point $z = c$ inside the fluid (with $0 < \arg z < \alpha$ and $|c| > 0$).

We recall that the transformation

$$\zeta = g(z) = z^{\pi/\alpha} \quad (3.2)$$

maps the given wedge $0 < \arg z < \alpha$ onto the half-space $\text{Im } \zeta > 0$, and is conformal everywhere inside the wedge except at the origin. The source is mapped to the point $\zeta = c^{\pi/\alpha}$ which must lie somewhere in the half-space $\text{Im } \zeta > 0$.

The transformed problem of a source in a half-space is easily solved by the method of images, and the solution is found to be

$$W(\zeta) = \frac{Q}{2\pi} \log(\zeta - c^{\pi/\alpha}) + \frac{Q}{2\pi} \log(\zeta - \overline{c^{\pi/\alpha}}). \quad (3.3)$$

Now reversing the transformation, we find the complex potential

$$w(z) = W(z^{\pi/\alpha}) = \frac{Q}{2\pi} \log(z^{\pi/\alpha} - c^{\pi/\alpha}) + \frac{Q}{2\pi} \log(z^{\pi/\alpha} - \overline{c^{\pi/\alpha}}). \quad (3.4)$$

In particular, if we set $\alpha = \pi/2$, then (3.4) becomes

$$w(z) = \frac{Q}{2\pi} \log(z^2 - c^2) + \frac{Q}{2\pi} \log(z^2 - \bar{c}^2). \quad (3.5)$$

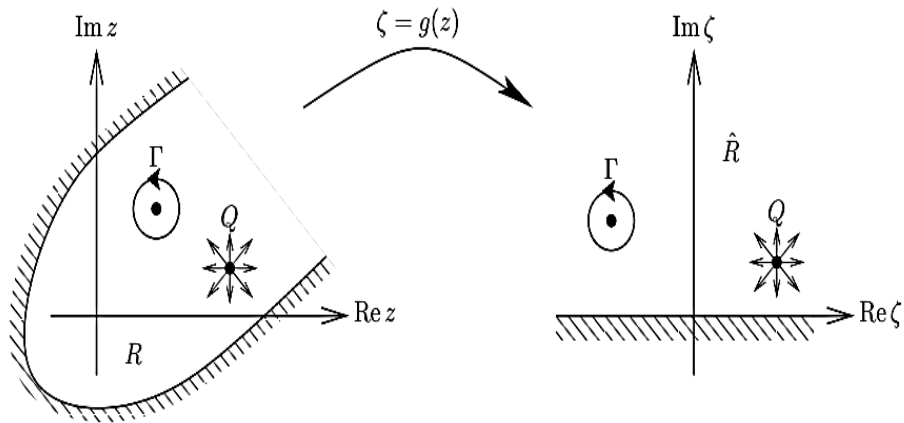


Figure 3.1: Schematic of a conformal mapping $\zeta = g(z)$ mapping a region R in the z -plane to the upper half-plane $\hat{R} = \{\zeta : \text{Im } \zeta > 0\}$ in the ζ -plane.

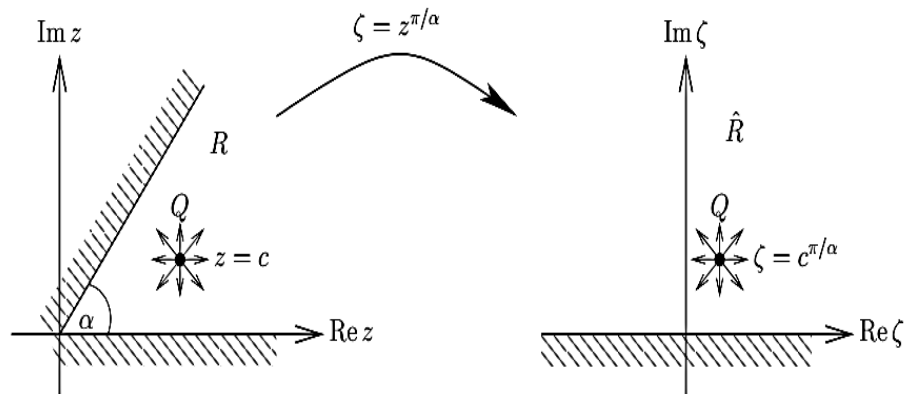


Figure 3.2: Schematic of the conformal mapping $\zeta = z^{\pi/\alpha}$ mapping the wedge $R = \{z : 0 < \arg z < \alpha\}$ in the z -plane to the upper half-plane $\hat{R} = \{\zeta : \text{Im } \zeta > 0\}$ in the ζ -plane.

The arguments of the logs are easily factorised to give

$$w(z) = \frac{Q}{2\pi} \log(z - c) + \frac{Q}{2\pi} \log(z + c) + \frac{Q}{2\pi} \log(z - \bar{c}) + \frac{Q}{2\pi} \log(z + \bar{c}), \quad (3.6)$$

which reproduces the result obtained for a quadrant in Section 2 by generalising the method of images.

3.1.2 Background theory

The above example illustrates the following important points that underpin the method.

1. **Conformal maps** are defined to be functions $\zeta = g(z)$ where $g(z)$ is *holomorphic* in R and $dg/dz \neq 0$ in R . We will be concerned with pairs of domains R and \hat{R} for which the map g defines a bijection between R and \hat{R} . The two domains are then said to be *conformally equivalent*.

2. Conformal maps **preserve angles**. We therefore expect the mapping not to be conformal at isolated *corners* in the boundary of R , where the angle is altered by the transformation. In Example 3.1, the mapping $\zeta = g(z)$ is not conformal at $z = 0$, where the angle is transformed from α to π .
3. If the boundary $\partial\hat{R}$ is a streamline in the ζ -plane, then the corresponding boundary ∂R is a streamline in the z -plane (and *vice versa*).

Proof If $\partial\hat{R}$ is a streamline, then $\text{Im } W(\zeta) = C$ for all $\zeta \in \hat{R}$, for some constant C . Since $\partial\hat{R}$ is the image of ∂R under the conformal mapping g , we can write $\partial\hat{R} = g(\partial R) = \{g(z) : z \in \partial R\}$. It follows that $\text{Im } w(z) = \text{Im } W(g(z)) = C$ for all $z \in \partial R$, and hence that ∂R is a streamline.

The converse result also holds since g is a bijection, so we can use exactly the same argument with g^{-1} . ■

4. A source of strength Q at $\zeta = g(c) \in \hat{R}$ in the ζ -plane corresponds to a source of the same strength Q at $z = c \in R$ in the z -plane (and *vice versa*).

Proof Suppose there is a source of strength Q at $\zeta = g(c) \in \hat{R}$, so that the complex potential takes the form

$$W(\zeta) \sim \frac{Q}{2\pi} \log(\zeta - g(c)) + O(1) \quad \text{as } \zeta \rightarrow g(c). \quad (3.7)$$

Since $z \mapsto g(z)$ is a bijection from R to \hat{R} , $\zeta \rightarrow g(c)$ if and only if $z \rightarrow c$, and it follows that

$$w(z) = W(g(z)) \sim \frac{Q}{2\pi} \log(g(z) - g(c)) + O(1) \quad \text{as } z \rightarrow c. \quad (3.8)$$

Furthermore, Taylor's Theorem gives

$$g(z) - g(c) \sim g'(c)(z - c) + O((z - c)^2) \quad \text{as } z \rightarrow c, \quad (3.9)$$

and hence

$$w(z) \sim \frac{Q}{2\pi} \log\left(g'(c)(z - c) + O((z - c)^2)\right) + O(1) \quad \text{as } z \rightarrow c, \quad (3.10)$$

where $g'(c) \neq 0$ since the mapping is supposed to be conformal. Therefore we can expand out the log to obtain

$$w(z) \sim \frac{Q}{2\pi} \log(z - c) + O(1) \quad \text{as } z \rightarrow c, \quad (3.11)$$

which implies the presence of a source of strength Q at $z = c$.

Again, the same argument works in reverse using g^{-1} instead of g . ■

Obviously, the same conclusion holds for vortices. However, the argument fails if we put a source or a vortex at a point where the mapping is not conformal, for example at an isolated corner in the boundary. Such cases require special treatment and will be avoided in this course.

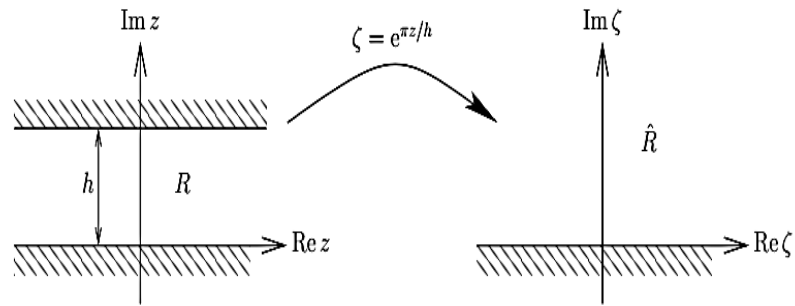


Figure 3.3: Schematic of the exponential conformal mapping $\zeta = e^{\pi z/h}$ mapping the channel $R = \{z : 0 < \text{Im } z < h\}$ in the z -plane to the upper half-plane $\hat{R} = \{\zeta : \text{Im } \zeta > 0\}$ in the ζ -plane.

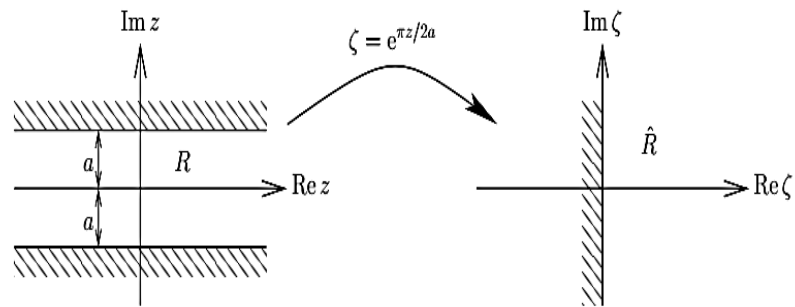


Figure 3.4: Schematic of the exponential conformal mapping $\zeta = e^{\pi z/2a}$ mapping the channel $R = \{z : -a < \text{Im } z < a\}$ in the z -plane to the right half-plane $\hat{R} = \{\zeta : \text{Re } \zeta > 0\}$ in the ζ -plane.

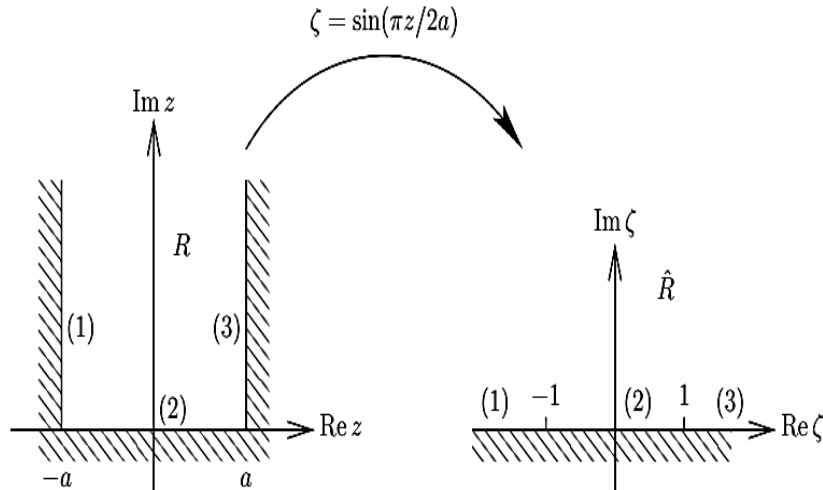


Figure 3.5: Schematic of the semi-infinite channel $R = \{z : \text{Im } z > 0, -a < \text{Re } z < a\}$ being transformed to the half-plane $\hat{R} = \{\zeta : \text{Im } \zeta > 0\}$ by the conformal mapping $\zeta = \sin(\pi z/2a)$.

3.1.3 Other examples of conformal maps

Exponential maps These are used to map a channel to a half-space. To start with, consider a channel of width h occupying the region $0 < \text{Im } z < h$ in the z -plane. The mapping

$$\zeta = g(z) = e^{\pi z/h} \tag{3.12}$$

maps this to the upper half-plane $\text{Im } \zeta > 0$, as shown schematically in Figure 3.3. We can easily see this by writing a typical point in R as $z = x + iy$, where $0 < y < h$. The corresponding point in \hat{R} is $\zeta = e^{\pi x/h} e^{i\pi y/h} = r e^{i\theta}$, where $r > 0$ and $0 < \theta < \pi$. Hence \hat{R} is the region $0 < \arg \zeta < \pi$, that is, the upper half-plane $\text{Im } \zeta > 0$.

The exponential mapping is easily generalised to deal with other channel-shaped regions. For example, the shifted channel $-a < \text{Im } z < a$ is transformed to the right half-plane $\text{Re } \zeta > 0$ by the mapping $\zeta = e^{\pi z/2a}$, as shown schematically in Figure 3.4.

Trigonometric maps These are used to map a semi-infinite channel onto a half-space. Consider for example the region R shown in Figure 3.5, where $\text{Im } z > 0$ and $-a < \text{Re } z < a$. The key observation is that, if we define

$$\zeta = g(z) = \sin\left(\frac{\pi z}{2a}\right), \tag{3.13}$$

then the mapping $z \mapsto g(z)$ is conformal everywhere in R and on ∂R , except at the corners $z = \pm a$, where dg/dz is zero. It is plausible, then, that this mapping may have the desired effect of “opening out” the angles of these corners and thus transforming ∂R into a straight line.¹ We can confirm that this is the case by considering the fates of the

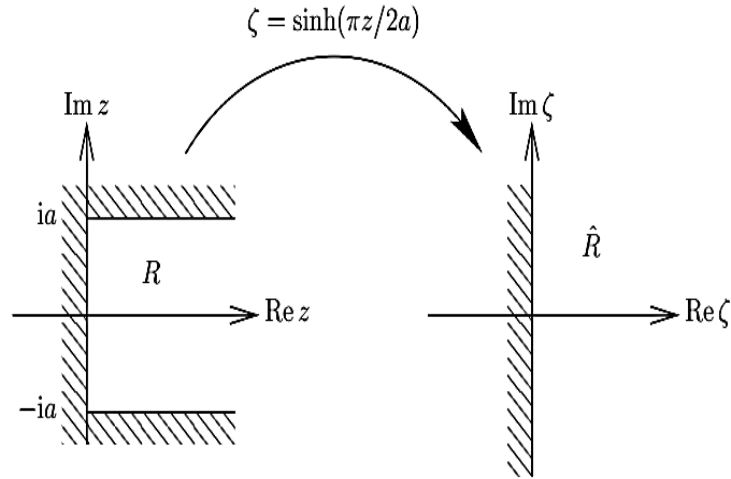


Figure 3.6: Schematic of the semi-infinite channel $R = \{z : \text{Re } z > 0, -a < \text{Im } z < a\}$ being transformed to the half-plane $\hat{R} = \{\zeta : \text{Re } \zeta > 0\}$ by the conformal mapping $\zeta = \sinh(\pi z/2a)$.

three line segments marked (1), (2) and (3) in Figure 3.5.

We can parametrise line (1) by writing $z = -a + iy$, where $y > 0$. Its image is therefore parametrised by

$$\zeta = \sin\left(-\frac{\pi}{2} + i\frac{\pi y}{2a}\right) = -\cosh\left(\frac{\pi y}{2a}\right), \quad (3.14)$$

which traces out the segment of the real- ζ -axis from $-\infty$ to -1 , as indicated in Figure 3.5. On line (2), we have $z = x \in (-a, a)$ and hence

$$\zeta = \sin\left(\frac{\pi x}{2a}\right), \quad (3.15)$$

which parametrises in the interval $(-1, 1)$ on the real- ζ -axis. Finally, the image of line (3) is given by

$$\zeta = \sin\left(\frac{\pi}{2} + i\frac{\pi y}{2a}\right) = \cosh\left(\frac{\pi y}{2a}\right), \quad (3.16)$$

where $y > 0$, and this describes the segment $(1, \infty)$ on the real- ζ -axis.

These calculations establish that the boundary ∂R gets mapped to the real axis in the ζ -plane. It only remains to decide whether R is mapped to the upper or the lower half-plane, and this can be determined by considering just one point. For example, the point $z = i \in R$ is mapped to $\zeta = i \sinh(\pi/2)$, which has positive imaginary part, and it follows that the image of R is the upper half-plane $\text{Im } \zeta > 0$, as indicated in Figure 3.5.

Other semi-infinite channel geometries can be handled using generalisations of (3.13). For example, the channel $\{z : \text{Re } z > 0, -a < \text{Im } z < a\}$ is transformed to the right half-plane by the mapping

$$\zeta = g(z) = \sinh(\pi z/2a), \quad (3.17)$$

as shown schematically in Figure 3.6. Again, the key to choosing the right map is to identify the corners where dg/dz should be zero.

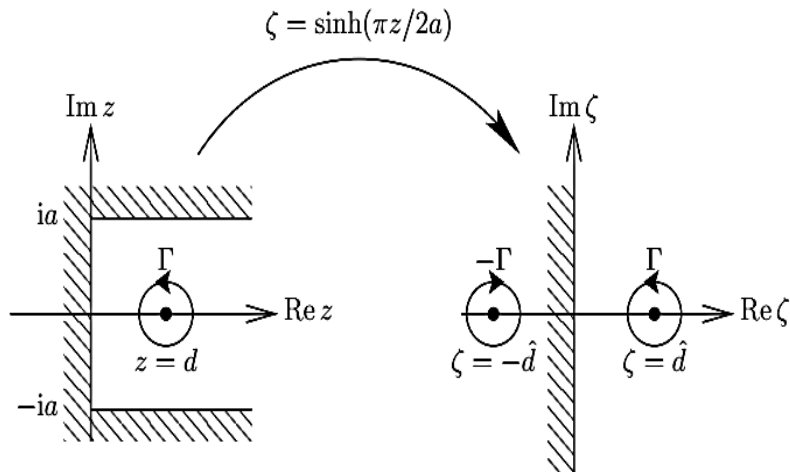


Figure 3.7: Schematic of a vortex at $z = d \in \mathbb{R}^+$ in the semi-infinite channel $R = \{z : \text{Re } z > 0, -a < \text{Im } z < a\}$ being transformed by the conformal mapping $\zeta = \sinh(\pi z/2a)$.

Example 3.2 A vortex in a semi-infinite channel

Consider the channel depicted in the left-hand z -plane in Figure 3.6. Now we wish to find the flow caused by the insertion of a vortex of strength Γ at the point $z = d \in \mathbb{R}^+$, as shown in Figure 3.7.

We use the mapping (3.17) to transform the channel on the right half-plane $\text{Re } \zeta > 0$. The vortex at $z = d$ is mapped to $\zeta = \hat{d} = \sinh(\pi d/2a)$. We can then satisfy the boundary condition on the imaginary ζ -axis by inserting an equal and opposite vortex at the image point $\zeta = -\hat{d}$, as shown in Figure 3.7. The complex potential is thus given by

$$W(\zeta) = -\frac{i\Gamma}{2\pi} \log(\zeta - \hat{d}) + \frac{i\Gamma}{2\pi} \log(\zeta + \hat{d}), \tag{3.18}$$

or, in terms of the original complex variable z ,

$$w(z) = W(g(z)) = \frac{i\Gamma}{2\pi} \left\{ -\log\left(\sinh\left(\frac{\pi z}{2a}\right) - \hat{d}\right) + \log\left(\sinh\left(\frac{\pi z}{2a}\right) + \hat{d}\right) \right\}. \tag{3.19}$$

The velocity components are thus given by

$$u - iv = \frac{dw}{dz} = -\left(\frac{i\Gamma}{2a}\right) \left(\frac{\cosh(\pi z/2a) \sinh(\pi z/2a)}{\sinh^2(\pi z/2a) - \sinh^2(\pi d/2a)}\right), \tag{3.20}$$

and a little simplification leads to

$$u - iv = \frac{i\Gamma}{4a} \left\{ \text{cosech}\left(\frac{\pi(z+d)}{2a}\right) - \text{cosech}\left(\frac{\pi(z-d)}{2a}\right) \right\}. \tag{3.21}$$

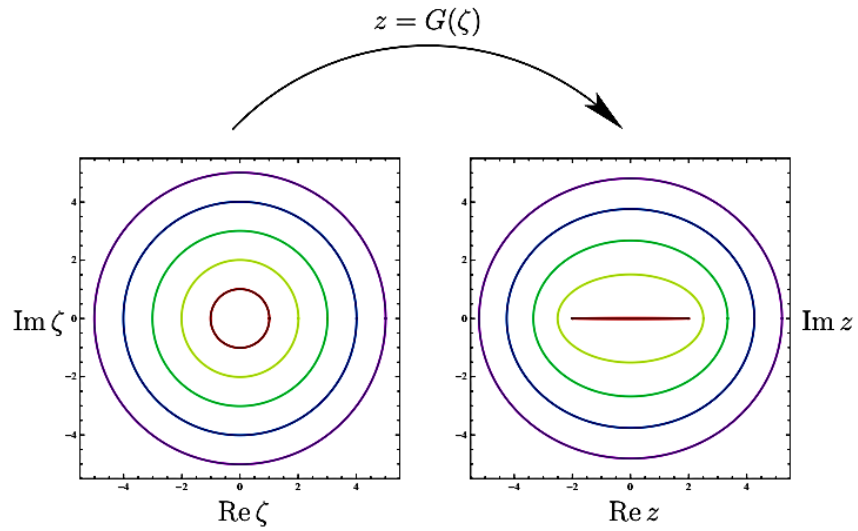


Figure 3.8: The images of circles $|\zeta| = r$ with $r \geq a$ under the Joukowski transformation $z = G(\zeta)$ given by (3.22). (Here $a = 1$.)