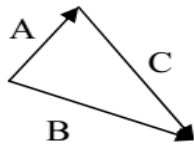


review of Vector Relation:

Consider two vectors:



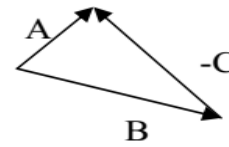
Addition

Vector addition: $\vec{A} + \vec{C} = \vec{B}$

Vector subtraction: $\vec{B} - \vec{C} = \vec{A}$

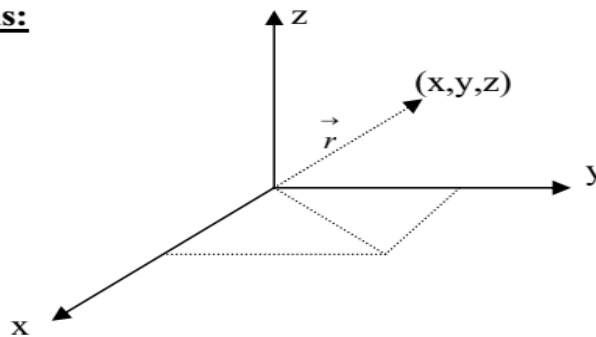
Scale product (Dot product): $A \bullet B = |A||B| \cos \theta = \text{scalar}$

Vector product (cross product): $A \times B = (|A||B| \sin \theta) \vec{e} = \text{vector product}$



Subtraction

Coordinate Systems:



$$\vec{r} = x \vec{i} + y \vec{j} + z \vec{k}$$

or you can write it as

$$\vec{r} = r_x \vec{i} + r_y \vec{j} + r_z \vec{k}$$

Where

$$r_x = x$$

$$r_y = y$$

$$r_z = z$$

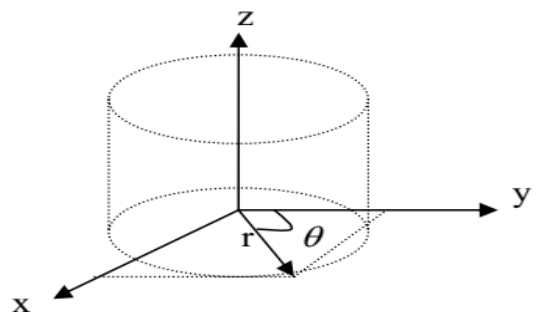
Cylindrical Coordinate:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$\Rightarrow x^2 + y^2 = (r \cos \theta)^2 + (r \sin \theta)^2$$

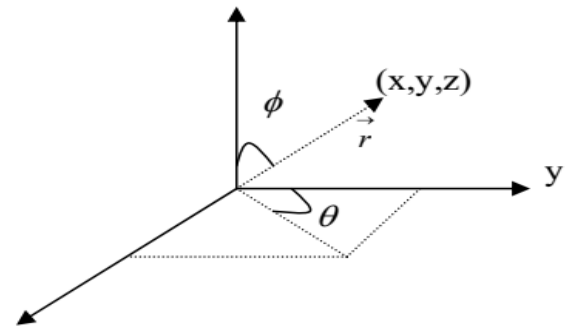


$$\begin{aligned}
 &= r^2 \cos^2 \theta + r^2 \sin^2 \theta \\
 &= r^2 (\cos^2 \theta + \sin^2 \theta) \\
 &= r^2 \\
 r^2 &= x^2 + y^2 \Rightarrow r = \sqrt{x^2 + y^2} \\
 \tan \theta &= \frac{y}{x} \Rightarrow \theta = \tan^{-1} \left(\frac{y}{x} \right)
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow r &= \sqrt{x^2 + y^2} \\
 \tan \theta &= \frac{y}{x} \\
 z &= z
 \end{aligned}$$

Spherical Coordinate:

$$\begin{aligned}
 x &= (r \sin \phi) \cos \theta = r \cos \theta \sin \phi \\
 y &= (r \sin \phi) \sin \theta = r \sin \theta \sin \phi \\
 z &= r \cos \phi = r \cos \theta
 \end{aligned}$$



Recall,

$$\vec{r} = x \vec{i} + y \vec{j} + z \vec{k} \Rightarrow r^2 = x^2 + y^2 + z^2$$

Proof:

$$\begin{aligned}
 \vec{r} &= r \cos \theta \sin \phi \vec{i} + r \sin \theta \sin \phi \vec{j} + r \cos \theta \vec{k} \\
 \vec{r} \cdot \vec{r} &= r^2 \cos^2 \theta \sin^2 \phi + r^2 \sin^2 \theta \sin^2 \phi + r^2 \cos^2 \theta \\
 \vec{r} \cdot \vec{r} &= r^2 \sin^2 \phi (\cos^2 \theta + \sin^2 \theta) + r^2 \cos^2 \theta \\
 \vec{r} \cdot \vec{r} &= r^2 = r^2 \sin^2 \phi + r^2 \cos^2 \theta \\
 \Rightarrow r^2 &= r^2
 \end{aligned}$$

scalar and Vector Fields:

scalar field can be expressed in terms of the coordinate system used.

Example: pressure $p(x, y, z, t)$

Temperature $t(x, y, z, t)$

for constant coordinate

Time t

Density $\rho(x, y, z, t)$

Vector field can also be expressed in terms of coordinate system

Example: velocity $\vec{v} = v_x \vec{i} + v_y \vec{j} + v_z \vec{k}$

$$v_x = v_x(x, y, z, t)$$

Where $v_y = v_y(x, y, z, t)$

$$v_z = v_z(x, y, z, t)$$

Scalar and Vector Products:

Suppose we have two vectors

$$\vec{A} = A_x \vec{i} + A_y \vec{j} + A_z \vec{k}$$

$$\vec{B} = B_x \vec{i} + B_y \vec{j} + B_z \vec{k}$$

Scalar product (dot product):

$$A \bullet B = A_x B_x + A_y B_y + A_z B_z ;$$

$$\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = \vec{k} \cdot \vec{k} = 1$$

$$\vec{i} \cdot \vec{j} = \vec{i} \cdot \vec{k} = \vec{k} \cdot \vec{i} = 0$$

$$\vec{j} \cdot \vec{i} = \vec{j} \cdot \vec{k} = \vec{k} \cdot \vec{j} = 0$$

Vector product (cross product)

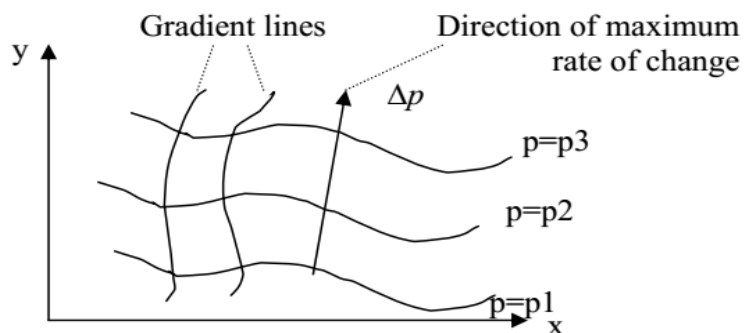
$$A \times B = \begin{bmatrix} i & j & k \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{bmatrix} = (A_y B_z - A_z B_y) \vec{i} - (A_x B_z - A_z B_x) \vec{j} + (A_x B_y - A_y B_x) \vec{k}$$

Similar thing can be done for the other coordinate systems.

Gradient and Scalar Field:

Suppose we have a scalar field i.e. pressure $p(x, y, z, t)$

The gradient of p is a vector with its magnitude being the maximum rate of change per unit length of the coordinate system at a given point and its direction is the maximum rate of change of p at a given point.



Mathematically, the gradient of p is

$$\Delta p = \frac{\partial p}{\partial x} \vec{i} + \frac{\partial p}{\partial y} \vec{j} + \frac{\partial p}{\partial z} \vec{k}$$

Divergence and a Vector Field:

Given a vector field i.e. velocity field

$$\vec{v} = v_x \vec{i} + v_y \vec{j} + v_z \vec{k}$$

the divergence of \vec{v} is

$$\Delta \bullet \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

we will proof shortly that the divergence is the time rate of change of the volume of a moving element per unit volume.

$$\int \vec{v} \bullet n ds = \int \left| \vec{v} \right| \left| n \right| \cos \theta ds = \left| \vec{v} \right| \left| n \right| \cos \theta \int ds = \left| \vec{v} \right| \cos \theta ds$$

Curl of Vector field:

The curl of a vector field \vec{v} is

$$\text{Curl of } \vec{v} = \Delta \times \vec{v} = \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{bmatrix} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \vec{i} - \left(\frac{\partial v_z}{\partial x} - \frac{\partial v_x}{\partial z} \right) \vec{j} + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \vec{k}$$

We will proof that in this chapter that the angular velocity ω of a fluid element is

$$\frac{1}{2} \text{curl}(\vec{v})$$