LOADS ON STRUCTURES:

For the purpose of designing any element, member or a structure, the following loads (actions) and their effects shall be taken into account, where applicable, with partial safety factors.

a) Dead loads;

b) Imposed loads (live load, crane load, snow load, dust load, wave load, earth pressure, etc);

c) Wind loads;

d) Earthquake loads;

e) Erection loads;

f] Accidental loads such as those due to blast, impact of vehicles, etc; and

g) Secondary effects due to contraction or expansion resulting from temperature changes, differential settlements of the structure as a whole or of its components, eccentric connections, rigidity of joints

- ✤ Dead Loads The self-weights of all permanent constructions and installations including the self-weight of all walls, partitions, floors, roofs, and other permanent fixtures acting on a member.
- Imposed (Live) Load The load assumed to be produced by the intended use or occupancy including distributed, concentrated, impact, vibration and snow loads but excluding, wind, earthquake and temperature loads.
- Wind Loads Load experienced by member or structure due to wind pressure acting on the surfaces.
- Earthquake Loads The inertia forces produced in a structure due to the ground movement during an earthquake.
- Erection Loads The actions (loads and eformations) experienced by the structure exclusively during erection.
- Accidental Loads Loads due to explosion, impact of vehicles, or other rare loads for which thestructure is considered to be vulnerable as per the user.

LOCAL BUCKLING AND SECTION CLASSIFICATION:

Introduction:

- ✓ Sections normally used in steel structures are I-sections, Channels or angles etc. which are called open sections, or rectangular or circular tubes which are called closed sections.
- ✓ These sections can be regarded as a combination of individual plate elements connected together to form the required shape.
- ✓ The strength of compression members made of such sections depends on their slenderness ratio.
- ✓ Higher strengths can be obtained by reducing the slenderness ratio i.e. by increasing the moment of inertia of the cross-section. Similarly, the strengths of beams can be increased, by increasing

the moment of inertia of the cross-section. For a given crosssectional area, higher moment of inertia can be obtained by making the sections thin-walled.

- ✓ As discussed earlier, plate elements laterally supported along edges and subjected to membrane compression or shear may buckle prematurely.
- ✓ Therefore, the buckling of the plate elements of the cross section under compression/shear may take place before the overall column buckling or overall beam failure by lateral buckling or yielding. This phenomenon is called **local buckling**.
- ✓ Thus, local buckling imposes a limit to the extent to which sections can be made thin-walled.

Consider an I-section column, subjected to uniform compression [Fig. 6(a)]. Therefore, in open sections such as I sections, the flanges which are outstands tend to buckle before the webs which are supported along all edges. Further, the entire length of the flanges is likely to buckle in the case of the axially compressed member under consideration, in the form of waves.

On the other hand, in closed sections such as the hollow rectangular section, both flanges and webs behave as internal elements and the local buckling of the flanges and webs depends on their respective width-thickness ratios. In this case also, local buckling occurs along the entire length of the member and the member develops a 'chequer board' wave pattern [Fig. 6(b)].

In the case of beams, the compression flange behaves as a plate element subjected to uniform compression and, depending on whether it is an outstand or an internal element, undergoes local buckling at the corresponding critical buckling stress. However, the web is partially under compression and partially under tension. Even the part in compression is not under uniform compression.

Therefore the web buckles as a plate subjected to inplane bending compression. Normally, the bending moment varies over the length of the beam and so local buckling may occur only in the region of maximum bending moment.

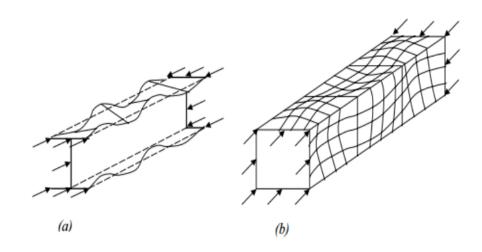


Fig. 6 Local buckling of Compression Members

Local buckling has the effect of reducing the load carrying capacity of columns and beams due to the reduction in stiffness and strength of the locally buckled plate elements. Therefore it is desirable to avoid local buckling before yielding of the member. Most of the hot rolled steel sections have enough wall thickness to eliminate local buckling before yielding.

However, fabricated sections and thin-walled cold-formed steel members usually experience local buckling of plate elements before the yield stress is reached. It is useful to classify sections based on their tendency to buckle locally before overall failure of the member takes place. For those cross-sections liable to buckle locally, special precautions need to be taken in design.

However, it should be remembered that local buckling does not always spell disaster. Local buckling involves distortion of the cross-section. There is no shift in the position of the cross-section as a whole as in global or overall buckling. In some cases, local buckling of one of the elements of the cross section may be allowed since it does not adversely affect the performance of the member as a whole. In the context of plate bucking, it was pointed out that substantial reserve exists plates beyond the point of elastic strength in buckling. Utilization of this reserve capacity may also be the objective of design.

Therefore, local buckling may be allowed in some cases, provided due care is taken to estimate the reduction in the capacity of the section due to it.

BASIC CONCEPTS OF PLASTIC THEORY:

Before attempting the classification of sections, the basic concepts of plastic theory will be introduced. More detailed descriptions can be found in subsequent chapters.

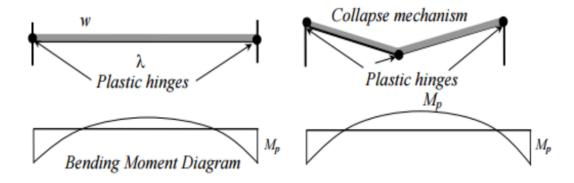


Fig. 7 Formation of a Collapse Mechanism in a Fixed Beam

Consider a beam with both ends fixed and subjected to a uniformly distributed load of w per meter length as shown in Fig. 7(a). The elastic bending moment at the ends is $wl^2/12$ and at mid-span is $wl^2/24$, where l is the span.

The stress distribution across any cross section is linear As w is increased gradually, the bending moment at every section increases and the stresses also increase. At a section close to the support where the bending moment is maximum, the stresses in the extreme fibers reach the yield stress.

The moment corresponding to this state is called the first yield moment My, of the cross section. But this does not imply failure as the beam can continue to take additional load. As the load continues to increase, more and more fibers reach the yield. Eventually the whole of the cross section reaches the yield stress .The moment corresponding to this state is known as the plastic moment of the cross section and is denoted by Mp.

The ratio of the plastic moment to the yield moment is known as the shape factor since it depends on the shape of the cross section. The cross section is not capable of resisting any additional moment but may maintain this moment for some amount of rotation in which case it acts like a plastic hinge. If this is so, then for further loading, the beam, acts as if it is simply supported with two additional moments Mp on either side, and continues to carry additional loads until a third plastic hinge forms at mid-span when the bending moment at that section reaches Mp.

The beam is then said to have developed a collapse mechanism and will collapse as shown in Fig 7(b). If the section is thin-walled, due to local buckling, it may not be able to sustain the moment for additional rotations and may collapse either before or soon after attaining the plastic moment. It may be noted that formation of a single plastic hinge gives a collapse mechanism for a simply supported beam.

The ratio of the ultimate rotation to the yield rotation is called the rotation capacity of the section. The yield and the plastic moments together with the rotation capacity of the cross-section are used to classify the sections.

SECTION CLASSIFICATION:

Sections are classified depending on their moment-rotation characteristics (Fig. 8). The codes also specify the limiting width-thickness ratios $\beta = b/t$ for component plates, which enables the classification to be made.

Plastic cross-sections: Plastic cross-sections are those which can develop their full plastic moment Mp and allow sufficient rotation at or above this moment so that redistribution of bending moments can take place in the structure until complete failure mechanism is formed ($b/t \le \beta 1$) (see Fig. 9).

Compact cross-sections: Compact cross-sections are those which can develop their full-plastic moment Mp but where the local buckling prevents the required rotation at this moment to take place ($\beta 1 < b/t < \beta 2$).

Semi-compact cross-sections: Semi-compact cross-sections are those in which the stress in the extreme fibers should be limited to yield stress because local buckling would prevent the development of the full-plastic moment Mp. Such sections can develop only yield moment My ($\beta 2 < b/t \le \beta 3$).

Slender cross-sections: Slender cross-sections are those in which yield in the extreme fibers cannot be attained because of premature local buckling in the elastic range ($\beta 3 < b/t$).

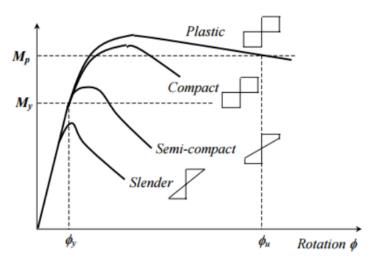


Fig. 8 Section Classification based on Moment-Rotation Characteristics

It should be remembered that even for steels with a large yield plateau, some strain hardening effects are likely to take place and the maximum moment is likely to be larger than Mp for plastic and compact sections. In such cases, the rotation capacity may be taken as the ratio of the rotation when the moment capacity drops back to Mp to the rotation at yield.

The relationship between the moment capacity Mu and the compression flange slenderness b/t indicating the β limits is shown in Fig. 9. In this figure, the value of Mu for semi-compact sections is conservatively taken as My. In the above classification, it is assumed that the web slenderness d/t is such that its buckling before yielding is prevented. It should be noted that the entire web may not be in uniform compression and if the neutral axis lies in the web, a part of the web may actually be in tension.

In this case, the slenderness limits are somewhat relaxed for the webs. Since the above classification is based on bending, it cannot be used for a compression member. The only criterion required is whether the member is slender or not. However, in practice, it is considered to be prudent to use compact or plastic sections for members carrying predominantly compressive loads.

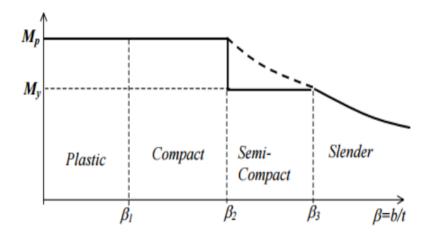


Fig 9. Section classification based on b/t ratio

LIMITS ON WIDTH-THICKNESS RATIO:

If the flanges and webs of cross-sections are considered to be plates under compression, their limiting width-thickness ratios can be obtained by equating the critical buckling stress to the yield stress. However, such an approach disregards a number of factors such as the actual support restraint provided by the adjoining plate element and the residual stresses and initial imperfections.

Therefore, the limiting width-thickness ratios $\beta 1$, $\beta 2$ and $\beta 3$ are useful for designers and are normally arrived at by validation in the testing laboratory. The limiting width-thickness ratios for different sections as per IS: 800, 2007 are given in Table 3.

The various extents of widths and thicknesses for different cross sections have been defined in Fig 10. Local buckling can be prevented, by controlling the width-thickness ratio. One way of doing this is by adopting higher thickness of the plate.

This method is adopted in rolled steel sections. However in the case of built-up sections and cold-formed sections, longitudinal stiffeners are provided which divide the total width into a number of smaller widths. The buckling of stiffened plates is beyond the scope of this chapter.

| Compression element | | | | Class of Section | | |
|---|--|---|--|---|---|--|
| | | | Ratio | Plastic (<i>B</i> _l) | Compact (B2) | Semi-compact (B) |
| Outstanding element of compression flange Internal element of compression flange | | Rolled section | | 9.48 | 10.56 | 15.76 |
| | | Welded section | | 8.45 | 9.48 | 13.65 |
| | | Compression due to bending | | 29.3 <i>c</i> | 33.56 | 428 |
| | | | b/ 1j | Not applicable | | |
| Neutral | Neutral axis at mid-depth | | d/t _w | 848 | 1056 | 1268 |
| | | If r ₁ is | d/Iw | 848 | 105.0s | |
| | | negative. | | - · · · · | | 126.06 |
| Genera | If r ₁ is | | d/tw | Dut ≤428 | 1+1.5r | $1+2r_2$ but $\leq 42\varepsilon$ |
| | | positive . | | | but ≤42ε | 041 3 420 |
| Axial compression | | d/1, | Not applicable | | | |
| Web of a channel | | | d/Iw | 428 | 428 | 428 |
| Angle, compression due to bending | | | b/1 | 9.48 | 10.56 | 15.78 |
| (Both criteria should be satisfied) | | | d/1 | 9.4 8 | 10.56 | 15.76 |
| Single angle, or double angles with the components separated, axial compression (All three criteria should be satisfied) | | | b/t d/t (b+d)/t | Not applicable | | 15.7ε 15.7ε 25ε |
| Outstanding leg of an angle in contact back-to-back in a double angle member Outstanding leg of an angle with its back in continuous contact with another component | | | d/t | 9.4 <i>ɛ</i> | 10.5 <i>e</i> | 15.7 <i>e</i> |
| subjected to moment | | | D/t | 4482 | 5562 | 8852 |
| Stem of a T-section, rolled or cut from a rolled I-or H-section | | | | 8.4 <i>ɛ</i> | 9.4 <i>ɛ</i> | 18.96 |
|) ^{1/2} hs for shear ween lateral e web, D m elements of ssification. ratio r ₁ and | bucklin support ean dian a cross-s r; are d | g in accordance wh is or between lateral neter of the element, nection can be in difj efined as | ten d/t > 67 t I support and Terent classes | : Where, b is th free edge, as a . In such cases | the width of the el ppropriate, t is the the section is cla | lement may be taken a he thickness of elemen |
| | ent of lange Neutral Genera Axial constant anel ession du should b or double eparated, eria shou eg of an a in a doub eg of an a contact of ming element ression ection, ro section ming element should b constant of ming element ratio r, and existication | on Well on Well Com to be to be Com to be Com to be Com Iange com Neutral axis a Com Generally Axial comprendition Axial comprendition Axial comprendition annel ession due to be ession due to be should be satis or double angle eparated, axial eria should be satis eria should be satis or double angle eg of an angle if in a double angle or eg of an angle if in a double angle eg of an angle if or contact with and CHS moment CHS ression CHS weldified contact with and homent CHS weldified contact which ming elements which on ween lateral support weldified eweb, D mean diant conserverse eweb, D mean diant consection ratio r, and r; are diant | Welded section Omegan of to bending Compression due to bending Inange Axial compression Neutral axis at mid-depth If r_1 is negative: Generally If r_1 is negative: Generally If r_1 is negative: Axial compression Integrative: Axial compression Integrative: Axial compression Integrative: Integrated, axial compression Integrated, axial compression Integrated, axial compression Integrated, axial compression or double angles with the eparated, axial compression Integrated, axial compression erg of an angle in contact in a double angle member Integrated, axial compression erg of an angle with its back contact with another CHS or built by welding moment ression CHS or built by welding ection, rolled or cut from a section Resentateral supports or between lateral supports or between laterad supports or between laterad supportsuport | Mathematical mWelded section b/t_f (Compression due to bendingent of hangeAxial compression b/t_f Neutral axis at mid-depth d/t_w Neutral axis at mid-depth d/t_w If r_1 is negative: d/t_w GenerallyIf r_1 is positive : d/t_w Axial compression d/t_w ession due to bending should be satisfied) b/t or double angles with the eparated, axial compression eria should be satisfied) b/t or double angles with the eparated, axial compression eria should be satisfied) b/t of an angle in contact in a double angle member eg of an angle with its back contact with another d/t moment ressionCHS or built by welding D/t ection, rolled or cut from a section D/t_f ming elements which exceeds semi-compact limits ar $t_f^{1/2}$ D/t_f hs for shear buckling in accordance when $dh > 67$ of ween lateral supports or between lateral support and te web, D mean diameter of the element, elements of a cross-section can be in different classes usification. ratio r_f and r_f are defined as taxial compressive stress r_{27} actual average as taxial compressive stress r_{27} actual average as | lement nRolled section b/t_f 9.4ε nWelded section b/t_f 8.4ε Compression due to bending b/t_f 29.3ε ent of langeAxial compression b/t_f Not apNeutral axis at mid-depth d/t_w 84ε If r_1 is negative: d/t_w 84ε GenerallyIf r_1 is positive : d/t_w 84ε Axial compression d/t_w 84ε Axial compression d/t_w Not apneel d/t_w 42ε ession due to bending should be satisfied) b/t 9.4ε or double angles with the eparated, axial compression eria should be satisfied) b/t 9.4ε or double angle in contact in a double angle member eg of an angle in contact in a double angle member d/t 9.4ε noment ressionCHS or built by welding D/t $44\varepsilon^2$ ection, rolled or cut from a section D/t_f 8.4ε ming elements which exceeds semi-compact limits are to be taken an $t_f^{1/2}$ b for shear buckling in accordance when $dh > 67 \varepsilon$. Where, b is the ween lateral support and free edge, as a e web. D mean diameter of the element.thermats of a cross-section can be in different classes. In such cases susfication. ratio r_1 and r_2 are defined as example compact size states states of the element. | lement mRolled section b/t_f 9.4ε 10.5ε mWelded section b/t_f 8.4ε 9.4ε Compression due to bending b/t_f 29.3ε 33.5ε ent of hangeAxial compression b/t_f Not applicableNeutral axis at mid-depth d/t_w 84ε 105ε Neutral axis at mid-depth d/t_w 84ε 105.0ε If r_1 is negative: d/t_w 84ε 105.0ε GenerallyIf r_1 is positive : d/t_w 84ε 105.0ε If r_1 is positive : d/t_w 84ε 105.0ε Axial compression d/t_w d/t_w 42ε Axial compression d/t_w 42ε 42ε ession due to bending b/t 9.4ε 10.5ε or double angles with the eparated, axial compression d/t 9.4ε 10.5ε or double angle in contact in a double angle member eg of an angle in contact in a double angle member d/t 9.4ε 10.5ε noment ressionCHS or built by welding D/t $44\varepsilon^2$ $55\varepsilon^2$ ection, rolled or cut from a section D/t_f 8.4ε 9.4ε noment in a double angle member eed of an angle with its back contact with another D/t_f 8.4ε 9.4ε noment ressionCHS or built by welding D/t_f 8.4ε 9.4ε noment in a double angle member eetion, rolled or cut from a section D/t_f 8.4ε 9.4ε nri |

Table 3.Limits on width to thickness ratio of plate elements

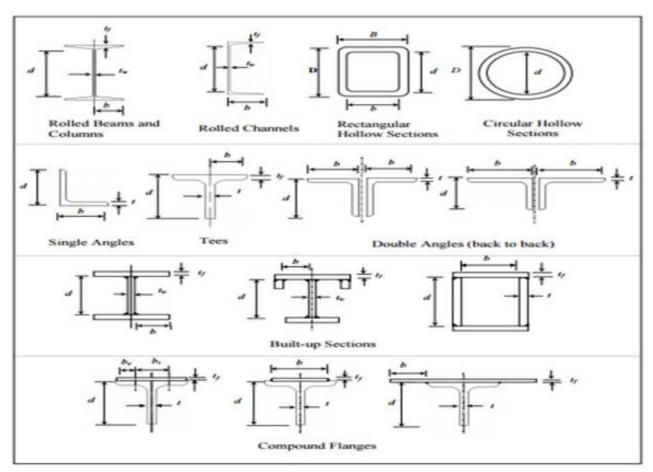


Fig 10.Dimensions of sections

It may be noted that semi-compact and slender members cannot be used in plastic design. In fact, only plastic sections can be used in indeterminate frames forming plastic collapse mechanisms while compact sections can be used in simply supported beams failing after reaching Mp at one section.

In elastic design, semi-compact sections may be used with the understanding that they will fail at My. Slender sections also have a stiffness problem and are normally not preferred in hot-rolled structural steel work. However, they are extensively used in cold-formed members and the manufacturer's literature may be consulted while using them. Plate girders are usually designed taking advantage of the tension field approach to achieve economy.