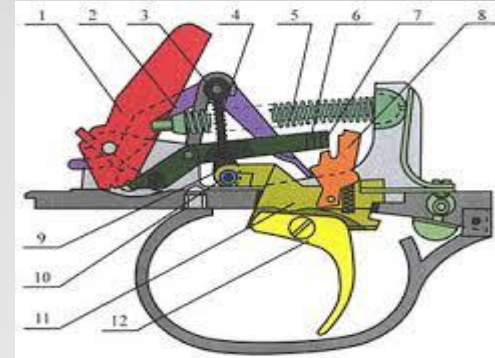
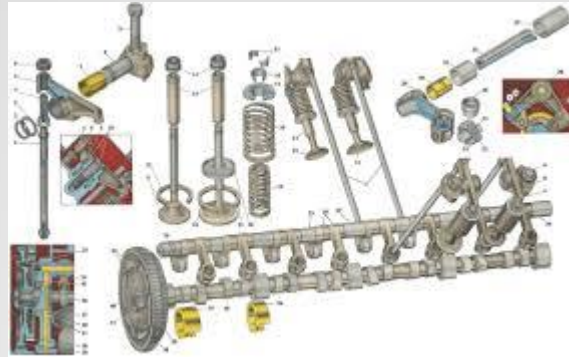
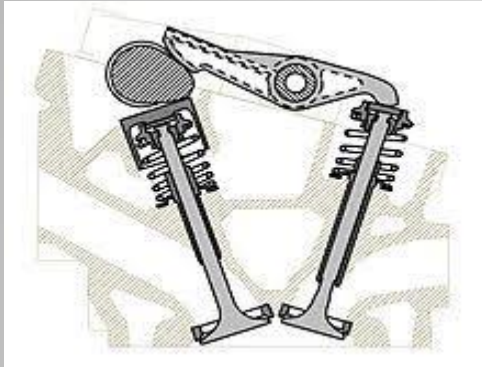
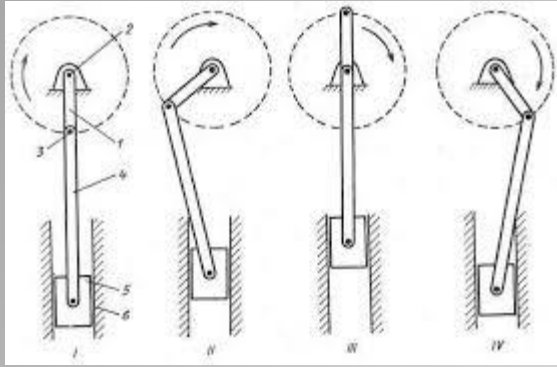


Ma'ruza №12

**MEXANIZMLAR VA MASHINALAR NAZARIYASI.
MEXANIZMLARNING ASOSIY TURLARI. KINEMATIK
JUFTLAR KLASSIFIKATSIYASI.**

● Reja:

- Richagli mexanizmlar tuzilishi va bo'g'inlari
- Oily va quyi kinematik juftlar
- Kinematik juftlarning sinflari



Kinematik juft

```
graph TD; A[Kinematik juft] --> B[Quyi kinematik juft]; A --> C[Oliy kinematik juft]; B --> D[Agar bog\'lanish elementi sirtdan iborat bo\'lsa]; B --> E[Agar bog\'lanish elementi nuqta yoki chiziqdan iborat bo\'lsa];
```

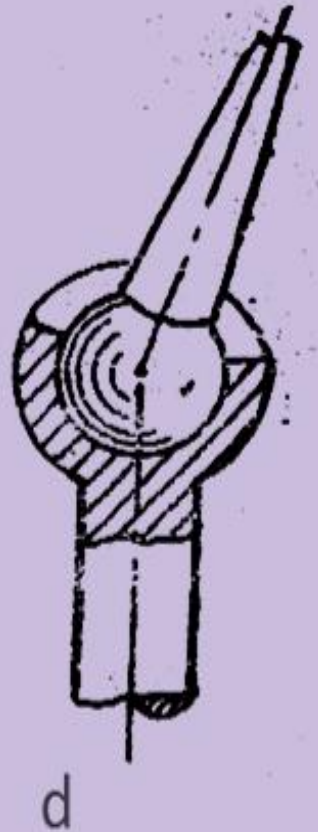
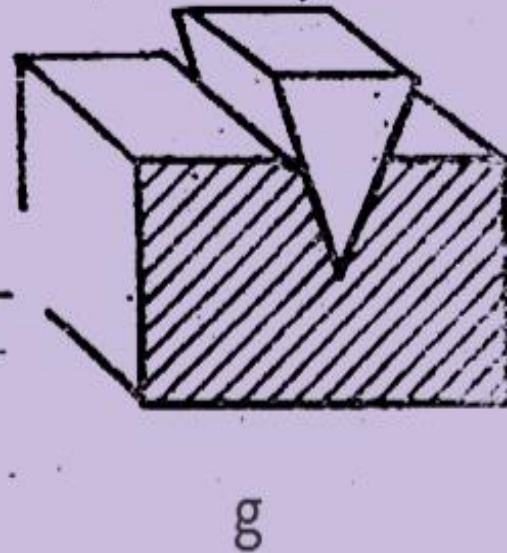
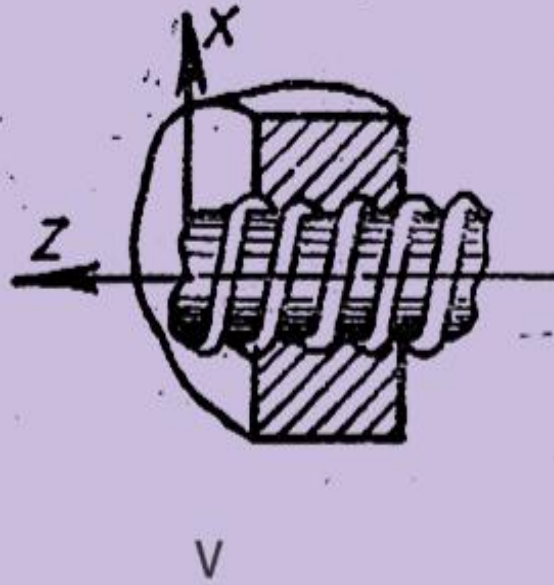
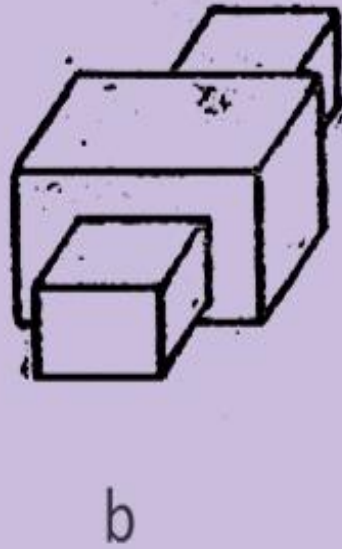
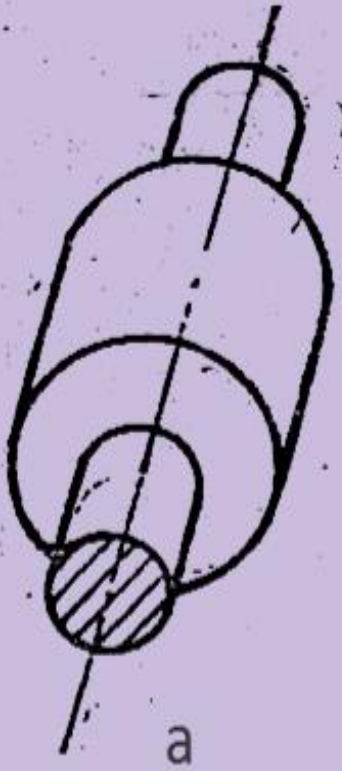
Quyi kinematik juft

Oliy kinematik juft

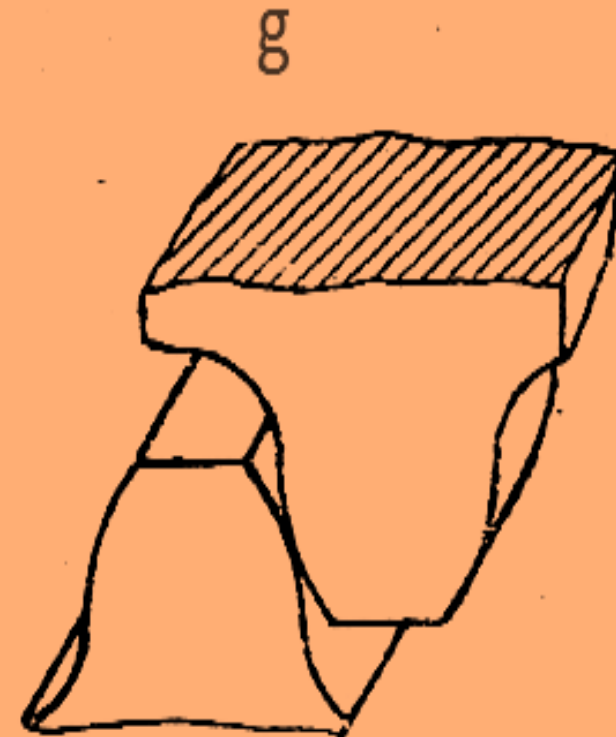
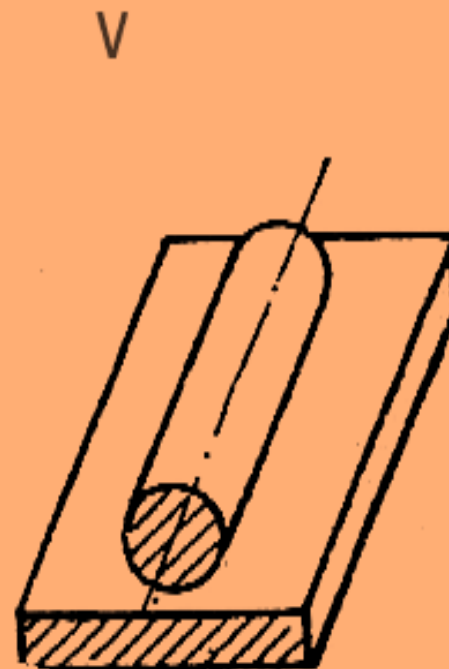
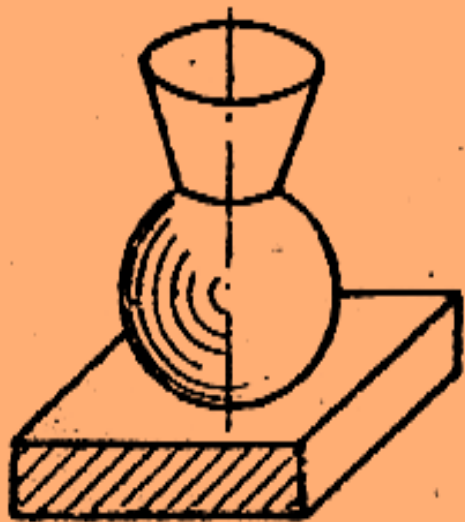
Agar bog\'lanish
elementi sirtdan iborat
bo\'lsa

Agar bog\'lanish elementi
nuqta yoki chiziqdan iborat
bo\'lsa

Quyî kinematik juftlar



Oliy kinematik juftlar



KINEMATIK JUFTLIK

FAZODAGI KINEMATIK JUFTLIK

Erkinlik darajasi
X, Y, Z o'qlariga
nisbatan ko'pi
bilan 5 ta

TEKISLIKDAGI KINEMATIK JUFTLIK

Erkinlik darajasi
X, Y, o'qlariga
nisbatan ko'pi
bilan 2 ta

Kinematik juftlar, tarkibidagi bo'g'inlarning nisbiy harakatiga qo'yilgan soniga qarab, 5 ta sinfga bo'linadi.

Bunda bog'lanishlar soni quyidagicha aniqlanadi.

$$C = 6 - H$$

H – bo'g'inning nisbiy harakatidagi erkinlik darajasi.

Kinematik
juftlar sinfi

1-sinf kinematik juft

P1

2-sinf kinematik juft

P2

3-sinf kinematik juft




P3


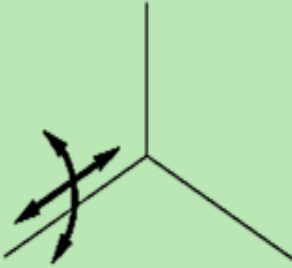
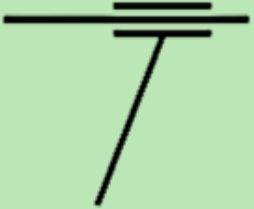
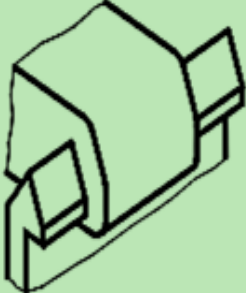
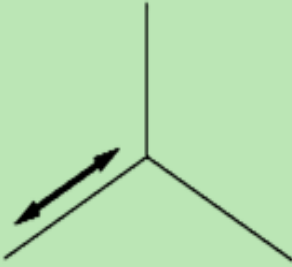


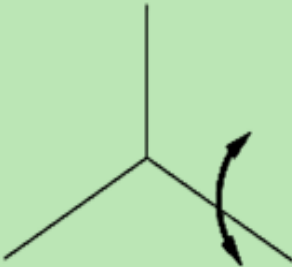

4-sinf kinematik juft

P4

5-sinf kinematik juft

P5

Klass	Bog'lanish miqdori	Harakatchanlik miqdori	Kinematik juft nomi	Kinematik juftning ko'rinishi	Bir zvenoning ikkinchisiga nisbatan bo'lish mumkin bo'lgan harakatlar	Kinematik juftlarning sxematik ko'rinishi
I	1	5	Shar-tekislik			
II	2	4	Silindr-tekislik			
III	3	3	Sferik			

IV	4	2	Silindrik			
V	5	1	Ilgarilanuvchi			
V	5	1	Aylanuvchi			

Shar-tekislik juftlik sinfini aniqlab ko'ramiz: $H=5$;
 $S=6-5=1$

Demak, 1 – sinf, oily kinematik juft ekan.







Slindr-tekis kinematik juftni sinfini aniqlab
ko'ramiz: $H=4$; $S=6-4=2$

Demak, 2 – sinf, oily kinematik juft ekan.

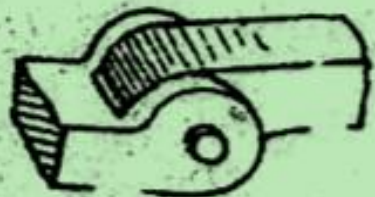
Ilgarilanma kinematik juftni sinfini aniqlab
ko'ramiz: $H=1$; $S=6-1=5$

Demak, 5 – sinf, quyi kinematik juft ekan.

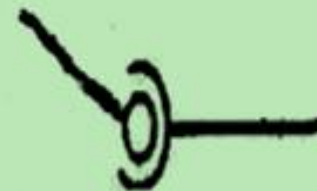
Kinematik sxemada ishlatiladigan shartli belgilar:

Nomi	Shakli	Shartli belgisi
Val, o'q, valik, sterjen, shatun va boshqalar		
Sterjenning qo'zg'almas qilib maxkamlanishi		
Sterjenning bikr qilib birlashtirilishi		

Sterjenning sharnir
yordamida birlashtirilishi

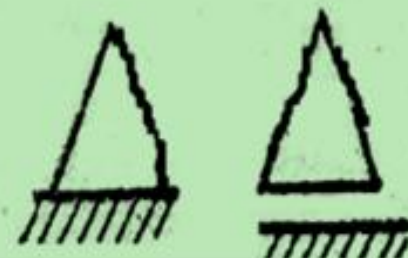


Sterjenning shar
yordamida birlashtirilishi



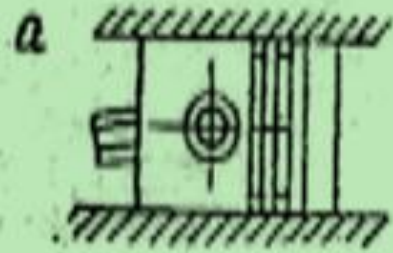
Sterjen uchun tayanch
(sto'yka):

a) qo'zg'almas

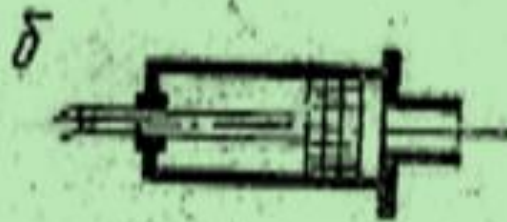


Silindr p'rshn bilan
qo'shilganda

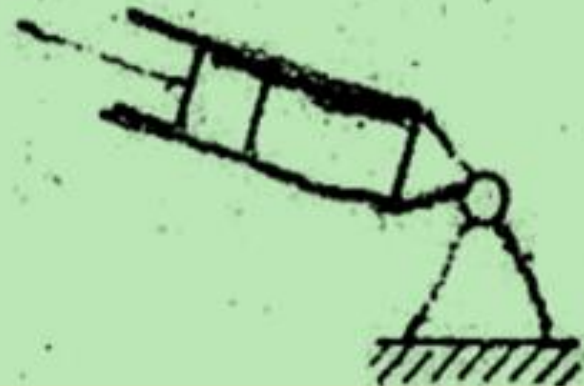
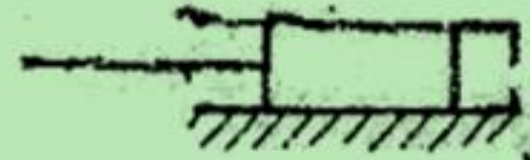
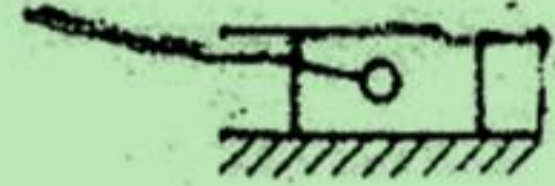
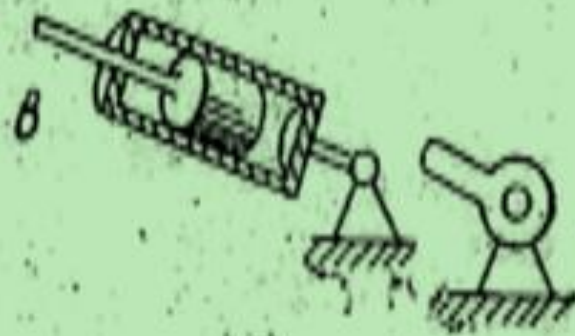
a) polzunning shatunga
ulanishi



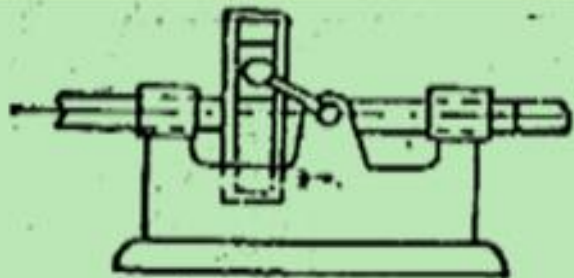
b) polzunning shtokka
ulanishi



v) polzunning tebranna
xarakatlanishi



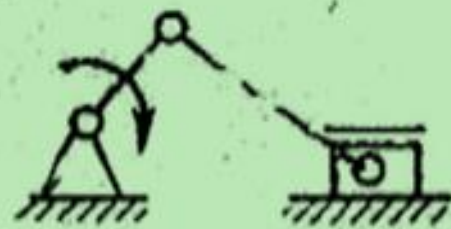
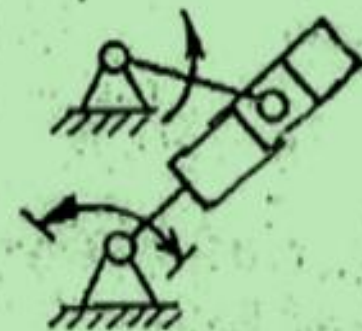
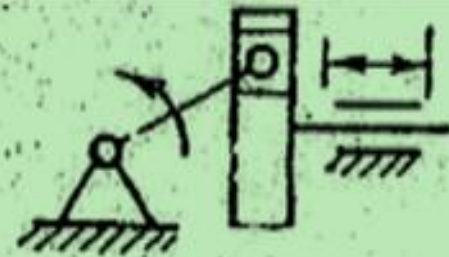
Ilgarilanma
xarakatlanuvchi kulisali
mexanizm



Tebranma (burilma)
xarakat qiluvchi kulisali
mexanizm



Krivoship polzunli
exanizm



Ilmli kishi hor bo'lmas.