

**ENG-302 -SOLID MECHANICS**

**ST. PAUL'S UNIVERSITY  
DEPARTMENT OF ENGINEERING**

**CAT I**

**ANSWER ALL QUESTIONS**

## QUESTION ONE

**The polar decomposition theorem.** This is a central theorem in mechanics. To prove it we will use the square root theorem (without proof).

**Thm\*:** If  $\mathbf{S}$  is a positive definite, symmetric second-order tensor, then there exists a unique positive definite symmetric second-order tensor  $\mathbf{U}$  such that  $\mathbf{U}^2 = \mathbf{S}$ .

Equipped with this result, the problem is to prove the following theorem.

**Thm:** (Polar decomposition). If  $\mathbf{F}$  is a second order tensor such that  $\det \mathbf{F} > 0$ , then there exist unique, positive definite, symmetric tensors,  $\mathbf{U}$  and  $\mathbf{V}$ , and a unique proper orthogonal tensor  $\mathbf{R}$  such that

$$\mathbf{F} = \mathbf{R}\mathbf{U} = \mathbf{V}\mathbf{R}. \quad (1)$$

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### SOLUTION

Show that  $\mathbf{F}^T \mathbf{F}$  is symmetric and positive definite. Then you can apply the square root theorem  $\mathbf{U}^2 = \mathbf{F}^T \mathbf{F}$ . Then define  $\mathbf{R} = \mathbf{F}\mathbf{U}^{-1}$ . Show that  $\mathbf{R}$  is proper orthogonal, establishing  $\mathbf{R}$  as a rotation. Explain why the decomposition is unique.

To establish the left polar decomposition, let  $\mathbf{Q} = \mathbf{V}^{-1} \mathbf{F}$ . Then by arguments similar to those above deduce that  $\mathbf{Q}$  is also a rotation. We then have  $\mathbf{F} = \mathbf{R}\mathbf{U} = \mathbf{V}\mathbf{Q}$ . Find an argument to show that  $\mathbf{R} = \mathbf{Q}$ .

**QUESTION TWO - 10 Marks**

Find the left and right polar decompositions of the matrices

$$(i) \begin{pmatrix} 2 & -3 \\ 1 & 6 \end{pmatrix} \quad (ii) \begin{pmatrix} 1 & -1 & 3 \\ 1 & 1 & 0 \\ -1 & 1 & 3 \end{pmatrix}. \quad (2)$$

*Steps: The key is to first compute  $\mathbf{U}$  as the square root of  $\mathbf{F}^T\mathbf{F}$ . Once  $\mathbf{U}$  is known, compute  $\mathbf{R} = \mathbf{F}\mathbf{U}^{-1}$ . Once  $\mathbf{R}$  is known, compute  $\mathbf{V}$  as  $\mathbf{F}\mathbf{R}^T$ . Once you have done the small one by hand, you may try a symbolic program (Mathematica or Maple).*

**SOLUTION**

The steps are already outlined in the solution so we only give the results. **Note that** to compute  $\mathbf{U} = \sqrt{\mathbf{C}}$ , you have to compute the eigenvalues of  $\mathbf{C}$  which we call  $\lambda_i^2$  and the normalised eigenvectors of  $\mathbf{C}$ . The you obtain  $\mathbf{U} = \sum_i \lambda_i \mathbf{e}_i \otimes \mathbf{e}_i$ . For (i),

$$\text{For (i)} \quad \mathbf{C} = \mathbf{F}^T\mathbf{F} = \begin{pmatrix} 5 & 0 \\ 0 & 45 \end{pmatrix} \quad \mathbf{U} = \sqrt{\mathbf{C}} = \begin{pmatrix} \sqrt{5} & 0 \\ 0 & 3\sqrt{5} \end{pmatrix} \quad (3)$$

$$\mathbf{R} = \mathbf{F}\mathbf{U}^{-1} = \begin{pmatrix} \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} \end{pmatrix} \quad \mathbf{V} = \mathbf{F}\mathbf{R}^T = \begin{pmatrix} \frac{7}{\sqrt{5}} & -\frac{4}{\sqrt{5}} \\ -\frac{4}{\sqrt{5}} & \frac{13}{\sqrt{5}} \end{pmatrix} \quad (4)$$

$$\text{For (ii)} \quad \mathbf{C} = \mathbf{F}^T\mathbf{F} = \begin{pmatrix} 3 & -1 & 0 \\ -1 & 3 & 0 \\ 0 & 0 & 18 \end{pmatrix} \quad \mathbf{U} = \sqrt{\mathbf{C}} = \begin{pmatrix} 1 + \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} - 1 & 0 \\ \frac{1}{\sqrt{2}} - 1 & 1 + \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 3\sqrt{2} \end{pmatrix} \quad (5)$$

$$\mathbf{R} = \mathbf{F}\mathbf{U}^{-1} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{\sqrt{2}} \end{pmatrix} \quad \mathbf{V} = \mathbf{F}\mathbf{R}^T = \begin{pmatrix} 1 + \frac{3}{\sqrt{2}} & 0 & \frac{3}{\sqrt{2}} - 1 \\ 0 & \sqrt{2} & 0 \\ \frac{3}{\sqrt{2}} - 1 & 0 & 1 + \frac{3}{\sqrt{2}} \end{pmatrix} \quad (6)$$

If you want to practise your *Mathematica* skills, experiment with this program

```
F = {{1, -1, 3}, {1, 1, 0}, {-1, 1, 3}}
(* right Cauchy-Green strain tensor *)
CG = Transpose[F].F; CG // MatrixForm
λsq = Eigenvalues[CG]; v = Eigenvectors[CG];
(* normalise Eigenvectors *)
v[[1]] = Normalize[v[[1]]]; v[[2]] = Normalize[v[[2]]]; v[[3]] = Normalize[v[[3]]];
(* now evaluate  $\mathbf{U} = \sum_i \lambda_i \mathbf{e}_i \otimes \mathbf{e}_i$  *)
U = Sum[Sqrt[λsq[[i]]] TensorProduct[v[[i]], v[[i]], {i, 1, 3}]; U // MatrixForm
R = F.Inverse[U] // FullSimplify; R // MatrixForm
V = F.Transpose[R] // FullSimplify; V // MatrixForm
```

### QUESTION THREE - 10 Marks

Consider the simple shear

$$\mathbf{x}(\mathbf{X}) = (X_1 + \gamma X_2, X_2, X_3), \quad \gamma \geq 0. \quad (7)$$

Calculate the principal stretches, and show that the right polar decomposition of the deformation gradient is given by

$$F = \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ \sin \theta & \frac{1+\sin^2 \theta}{\cos \theta} & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad (8)$$

where  $\tan \theta = \frac{\gamma}{2}$ . Determine also the left polar decomposition. What are the Eulerian and Lagrangian axes?

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### SOLUTION

From the deformation map we can compute the deformation gradient  $\mathbf{F}$  and right Cauchy-Green strain tensor  $\mathbf{C}$

$$\mathbf{F} = \begin{pmatrix} 1 & \gamma & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \mathbf{C} = \mathbf{F}^T \mathbf{F} = \begin{pmatrix} 1 & \gamma & 0 \\ \gamma & 1 + \gamma^2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Taking the square  $\mathbf{U}$  in (8) and comparing with  $\mathbf{C}$  (in which we substitute  $\gamma = 2 \tan \theta$ ) shows that (8) is indeed the polar decomposition. This determines  $\mathbf{R}$  uniquely. The principal stretches are

$$\lambda_1 = 1 \quad \lambda_2 = 2 \tan \theta (\tan \theta - \sec \theta) + 1 \quad \lambda_3 = 2 \tan \theta (\tan \theta + \sec \theta) + 1 \quad (9)$$

The left polar decomposition is

$$\mathbf{F} = \mathbf{V} \mathbf{R} = \begin{pmatrix} \frac{1+\sin^2 \theta}{\cos \theta} & \sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (10)$$

You can confirm these results quite easily with *Mathematica*. Experiment with this:

```
F := {{1, γ, 0}, {0, 1, 0}, {0, 0, 1}}
CG = Transpose[F].F;
λsq = Eigenvalues[CG] /. γ -> 2 Tan[θ];
v = Eigenvectors[CG] /. γ -> 2 Tan[θ];
v[[1]] = v[[1]] // Normalize;
v[[2]] = v[[2]] // Normalize;
v[[3]] = v[[3]] // Normalize;
U = FullSimplify[ Sum[Sqrt[λsq[[i]]] TensorProduct[v[[i]], v[[i]]],
  {i, 1, 3}], Assumptions -> 0 < θ < Pi/2];
```

