

## LECTURE 12

**Payoff**

Source code: MCLib/base\_payoff\_statistics.hpp

```

1  template<class path_piece_out, class PM
2  >
3  class payoff
4  {
5  public:
6      typedef typename mc::path<path_piece_out, PM> path_out; //!< solution
7      virtual ~payoff() {}
8      virtual mc::bvector & operator() (path_out & poArg,
9      mc::bvector & bvOut)=0;
10     virtual unsigned int SizePayoff() const=0;
11 };

```

- ▶ `payoff` is an abstract class defining a framework for payoffs of the type  $f(S)$
- ▶ high-level functions take reference or pointer to `payoff`
- ▶ virtual members to be implemented in derived classes: `operator()`, `SizePayoff()`
- ▶ `operator()` take a solution path and a boost vector `bvOut` by reference and must return a reference to `bvOut`
- ▶ `SizePayoff()` returns the size of the payoff vector, can be 0 if the size is unknown before the call of `operator()` (this is subject to revision)

**European call - declaration**

Source code: MCLib/particular\_payoff\_statistics.hpp

```

1  class european_calls_payoff :
2      public mc::payoff<mc::bvector>
3  {
4  public:
5      european_calls_payoff(const mc::bvector & bvStrikes,
6      unsigned int ind=0);
7      mc::bvector & operator() (path_out & poArg,
8      mc::bvector & bvOut);
9      unsigned int SizePayoff() const;
10
11 private:
12     mc::bvector bvStrikes_; //!< vector of strikes
13     unsigned int ind_; //!< index of the underlying in path_piece for option
14     payoff

```

- ▶ `european_calls_payoff` is a particular class derived from `payoff`
- ▶ it stores a vector of strikes  $K = (K_1, \dots, K_n)$  in `bvStrikes_` and an index  $i$  in `ind_`
- ▶ `operator()` returns a vector of call payoff values:  $P = (P_1, \dots, P_n)$ , where

$$P_k = \max(S_T[i] - K_k, 0), \text{ for } k = 1, \dots, n$$

and  $S_T$  is the path piece of the solution path corresponding to time  $T$

## European call - implementation

Source code: MCLib/particular\_payoff\_statistics.cpp

```

1 pmc::european_calls_payoff::
2 european_calls_payoff(const mc::bvector & bvStrikes,
3     unsigned int ind)
4     : bvStrikes_(bvStrikes),
5       ind_(ind)
6     {}

```

- ▶ the constructor initialises the data members

```

1 unsigned int pmc::european_calls_payoff::SizePayoff() const {
2     return bvStrikes_.size();
3 }

```

- ▶ SizePayoff() returns the size of vector of strikes

```

1 mc::bvector & pmc::european_calls_payoff::
2 operator()(path_out & poArg, mc::bvector & bvOut)
3 {
4     const mc::bvector & underlying=poArg.find(mc::dyadic(0,0))->second;
5     size_t n=SizePayoff();
6     bvOut.resize(n);
7
8     for(size_t i=0; i<n; ++i)
9         bvOut[i]=std::max(underlying[ind_]-bvStrikes_[i],0.0);
10
11     return bvOut;
12 }

```

- ▶  $S_T$  is accessed using the `find()` member of `poArg` with the dyadic interval  $[0, 1]$
- ▶ `bvOut` is resized to the right size
- ▶ the loop evaluates each of the call payoffs
- ▶ a reference to `bvOut` is returned

Source code: MCLib/particular\_payoff\_statistics.hpp

```

1  class asian_discretely_sampled_payoff :
2      public mc::payoff<mc::bvector>
3  {
4      public:
5          asian_discretely_sampled_payoff(unsigned int iSamplingAccuracy,
6              unsigned int indY=0);
7          mc::bvector & operator() (path_out & poArg,
8              mc::bvector & bvOut);
9          unsigned int SizePayoff() const;
10     private:
11         unsigned int iSamplingAccuracy_;//!< the average is taken over a scale
12             of 2^(iSamplingAccuracy) steps
13         unsigned int indY_;//!< the index of the component to be averaged
14     };

```

- ▶ `asian_discretely_sampled_payoff` is another particular class derived from `payoff`
- ▶ Discretely sampled Asian call pays

$$\max \left( S_T[i] - \frac{1}{M} \sum_{k=1}^M S_{T_k2-M}[i], 0 \right)$$

- ▶ `iSamplingAccuracy_` stores  $M$
- ▶ `indY_` stores the index  $i$

Source code: MCLib/particular\_payoff\_statistics.cpp

```

1  mc::asian_discretely_sampled_payoff::
2  asian_discretely_sampled_payoff(unsigned int iSamplingAccuracy,
3      unsigned int indY)
4      : iSamplingAccuracy_(iSamplingAccuracy),
5        indY_(indY)
6  {}

```

- ▶ the constructor initialises the data members

```

1  unsigned int mc::asian_discretely_sampled_payoff::SizePayoff() const
2  {
3      return 1;
4  }

```

- ▶ `SizePayoff()` returns 1

```

1 mc::bvector & pmc::asian_discretely_sampled_payoff::
2 operator()(path_out & poArg, mc::bvector & bvOut)
3 {
4     bvOut.resize(SizePayoff());
5     mc::dyadic dyadStep(0, iSamplingAccuracy_);
6     unsigned int n=(1<<iSamplingAccuracy_)-1;
7     mc::scalar AvY(mc::scalar(0));
8     mc::scalar multiplier;
9     for(unsigned int i=0; i<n; ++i, ++dyadStep){
10        multiplier=mc::scalar(i)/mc::scalar(i+1);
11        AvY*=multiplier;
12        AvY+=((*(poArg.find(dyadStep))).second)[indY_]/mc::scalar(i+1);
13    }
14    bvOut[0]=std::max(((*(poArg.find(dyadStep))).second)[indY_]-AvY,
15                    mc::scalar(0));
16    return bvOut;
17 }

```

operator()

- ▶ bvOut is resized
- ▶ a compatible iSamplingAccuracy is computed
- ▶ the dyadic  $[0, 2^{-M}]$  is initialised
- ▶  $n=2^M$  using the bit shift operator << (note that it is not the ostream operator because the first argument is not an ostream)
- ▶ in the loop the average stock price is computed, note that both i and the dyadic interval dyadStep are incremented in each cycle
- ▶ the payoff value is written into bvOut
- ▶ a reference to bvOut is returned

Further classes derived from payoff declared in particular\_payoff\_statistics.hpp:

- ▶ asian\_continuously\_sampled\_payoff
- ▶ lookback\_discretely\_sampled\_payoff

and another one declared in particular\_ko\_payoff.hpp:

- ▶ knock\_out\_payoff

Source code: MCLib/particular\_ko\_payoff.hpp

```

1  template<typename ko_cond>
2  class knock_out_payoff : public mc::payoff<mc::bvector>
3  {
4  public:
5      typedef sptr::shared_ptr<mc::payoff<mc::bvector> > payoff_ptr;///!<smart
6      pointer to payoff
7      knock_out_payoff(payoff_ptr PtrPayoff,
8                      ko_cond KOCond,
9                      unsigned int iPathDepAccuracy=0);
10     knock_out_payoff(mc::payoff<mc::bvector> * PtrPayoff,
11                    ko_cond KOCond,
12                    unsigned int iPathDepAccuracy=0);
13     mc::bvector & operator() (path_out & poArg, mc::bvector & bvOut);
14     unsigned int SizePayoff() const;
15 private:
16     payoff_ptr PtrPayoffIfNotKO_;//!< points to the payoff component
17     ko_cond KOCond_;//!< template type function object, bool operator(
18     bvector) member is assumed
19     unsigned int iPathDepAccuracy_;//!< defines the scale on which the KO
20     kondition is checked
21 };

```

### General knock out payoffs - declaration

- ▶ knock\_out\_payoff is a particular class derived from payoff
- ▶ knock\_out\_payoff implements payoffs of the type

$$P(S) (1 - \mathbf{1}_{A(S_t, t \in \{k2^{-M}T | k=1, \dots, 2^{-M}\})})$$

where  $P(\cdot)$  is any payoff and  $A(\cdot)$  is a knock-out event, i.e. if  $A$  does not occur, the option pays  $P$ , otherwise it pays 0

- ▶ the member PtrPayoffIfNotKO\_ is the pointer to the payoff  $P(\cdot)$
- ▶ KOCond\_ is of type ko\_cond (the template type), implements  $\mathbf{1}_{A(\cdot)}$
- ▶ iPathDepAccuracy\_ defines the sampling accuracy, i.e.  $M$

**Implicit assumption** on particular ko\_cond objects - must have these members

```

1  bool operator() (const mc::bvector & bvArg) const;
2  void Reset () {}

```

- ▶ operator() takes a boost vector (particular solution path piece) and returns a bool
- ▶ Reset() might be used if the state of the ko\_cond is subject to changes

## General knock out payoffs - implementation

```

1  template<typename ko_cond>
2  mc::bvector & pmc::knock_out_payoff<ko_cond>::
3  operator() (path_out & poArg, mc::bvector & bvOut)
4  {
5      unsigned int iPathDepAccuracy=
6          std::min(iPathDepAccuracy_, poArg.MaxAccuracy());
7      KOCond_.Reset();
8      bool isNotKO(true);
9      mc::dyadic dyadStep(0, iPathDepAccuracy);
10     unsigned int i=0;
11     unsigned int iMaxSteps=(1<<iPathDepAccuracy);
12     while(isNotKO && i<iMaxSteps){
13         isNotKO= !(KOCond_(poArg.find(dyadStep)->second));
14         ++dyadStep;
15         ++i;
16     }
17     if(isNotKO)
18         return ((*PtrPayoffIfNotKO_)(poArg, bvOut));
19     else {
20         bvOut.resize(SizePayoff());
21         return (bvOut*=mc::scalar(0));
22     }
23 }

```

operator() implementation (previous slide)

- ▶ computing a compatible sampling accuracy
- ▶ reset KO condition
- ▶ defining loop variables
- ▶ while loops until KO condition is met or until  $T$  is reached
- ▶ if not knocked out, evaluate payoff
- ▶ if knocked out, return zero vector

```

1  class UpAndOut
2  {
3  public:
4      UpAndOut(mc::scalar sBarrier,
5              unsigned int ind=0);
6      bool operator() (const mc::bvector & bvArg) const;
7      void Reset() {}
8  private:
9      mc::scalar sBarrier_;//!< KO barrier
10     unsigned int ind_;//!< index of component triggering the KO
11 };

```

- ▶ required members: `operator()` and `Reset()`
- ▶ additional members: `sBarrier_ barrier  $B$` , `ind_ index  $i$`  of component triggering the knock out event
- ▶ knock out event occurs at time  $t$  if  $Y_t[i] \geq B$

Further knock out conditions implemented in `MCLib` declared in `particular_ko_conditions.hpp`

- ▶ `DoubleBarrier`
- ▶ `UpDownAndOut`

```

1 pmc::UpAndOut::UpAndOut(mc::scalar sBarrier,
2     unsigned int ind)
3     : sBarrier_(sBarrier), ind_(ind)
4     {}

```

- ▶ the constructor initialises the data members

```

1 bool pmc::UpAndOut::operator() (const mc::bvector & bvArg) const
2 {
3     return bvArg[ind_] >= sBarrier_;
4 }

```

- ▶ `operator()` returns true is  $Y_t[i] \geq B$

Source code: `MCLib/base_payoff_statistics.hpp`

```

1 template<typename path_piece_out, class PM
2 >
3 class time_dependent_payoff
4 {
5 public:
6     typedef mc::path<path_piece_out, PM> path_out; //!<solution path
7     virtual ~time_dependent_payoff() {}
8     virtual mc::bvector & operator() (path_out & pFactors,
9         const mc::dyadic & dTimeStep,
10         mc::bvector & bvValue)=0;
11     virtual unsigned int SizePayoff() const=0;
12 };

```

- ▶ `time_dependent_payoff` is an abstract class, defining the framework for payoffs of the type  $f(S., [s, t])$  where  $[s, t]$  is a dyadic interval
- ▶ high-level functions take reference or pointer to `time_dependent_payoff`
- ▶ the concept is similar to `payoff`
- ▶ the difference is in `operator()` that also takes a `dyadic` as argument

Source code: MCLib/particular\_payoff\_statistics.hpp

```

1  class time_dependent_put :
2      public mc::time_dependent_payoff<mc::bvector>
3  {
4  public:
5      time_dependent_put(const mc::bvector & bvArg,
6                          mc::bvector::size_type index=0);
7      mc::bvector & operator() (path_out & pFactors,
8                              const mc::dyadic & dTimeStep,
9                              mc::bvector & bvValue);
10     unsigned int SizePayoff() const;
11 private:
12     mc::bvector::size_type m_index;///< index of the underlying in
13     path_piece for option payoff
14     mc::bvector m_bvStrikes;///< vector of strikes
};

```

- ▶ time\_dependent\_put is a particular class derived from time\_dependent\_payoff
- ▶ this function object implements the time dependent payoff

$$f(S., [s, t]) = \max(K_i - S_t, 0)$$

for a vector of strikes  $K = (K_1, \dots, K_n)$

Source code: MCLib/particular\_payoff\_statistics.cpp

```

1  mc::bvector & pmc::time_dependent_put::
2  operator() (path_out & pFactors,
3              const mc::dyadic & dTimeStep,
4              mc::bvector & bvValue)
5  {
6      const mc::bvector & underlying=pFactors.find(dTimeStep)->second;
7      size_t n=SizePayoff();
8      bvValue.resize(n);
9      for(size_t i=0; i<n; ++i)
10         bvValue[i]=std::max(m_bvStrikes[i]-underlying[m_index], 0.0);
11
12     return bvValue;
13 }

```

- ▶ operator() looks up  $S_t$  in  $S$ .
- ▶ then computes the put payoff with each of the strikes, results are written into bvValue
- ▶ the function returns reference to bvValue

## Summary

### Key functions

- ▶ `path<path_piece>::find(dyadic dyad)` returns an iterator to the path piece corresponding to dyad
- ▶ `dyadic::dyadic(unsigned int k, unsigned int n)` - constructs  $[k2^{-n}, (k+1)2^{-n}]$
- ▶ `dyadic::operator++()` - increments  $k$  (does not leave  $[0, 1]$ )
- ▶ `dyadic::operator--()` - decrements  $k$  (does not leave  $[0, 1]$ )
- ▶ `dyadic::Accuracy()` returns  $n$
- ▶ `dyadic::Position()` returns  $k$
- ▶ `dyadic::GetLength()` returns  $2^{-n}$
- ▶ `1<<n` - bit shift operator

## Closing thoughts

*Bazinga!*

Sheldon Cooper